

TIME DELAY LENS MODELING CHALLENGE FOR THE HUBBLE CONSTANT ESTIMATION

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INTRODUCTION

Video Credit: Science, American Association for the Advancement of Science

The Hubble constant H_0 represents the current expansion rate of the Universe, as well as the age ($= H_0^{-1}$), size, and density of the Universe.

INTRODUCTION (CONT.)

But there have been several different estimates of H_0 from various methods.

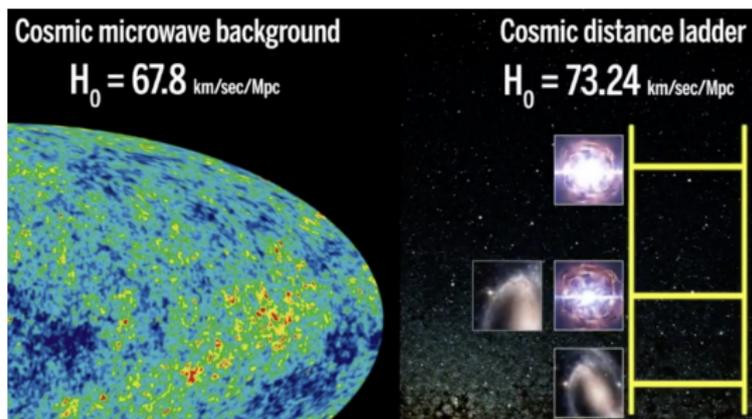


Image Credit: Science, American Association for the Advancement of Science

The most recent estimates from these two methods are

- ▶ CMB (Planck collaboration, 2016): $67.8 \pm 0.9 \text{ km s}^{-1}\text{Mpc}^{-1}$.
- ▶ CDL (Reiss et al., 2016): $74.3 \pm 2.1 \text{ km s}^{-1}\text{Mpc}^{-1}$.

Is this difference **true (new physics)** or **not (within statistical uncertainty)**?
Improving statistical accuracy or double-checking by independent methods.

TIME DELAY COSMOGRAPHY

Quasar is a highly luminous galaxy hosting a supermassive black hole at the center. Since it is extremely bright, it can be seen at a great distance.

Video Credit: Space.com

TIME DELAY COSMOGRAPHY (CONT.)

Video source: <https://www.youtube.com/watch?v=iE8x9kDHCFo>

Strong gravitational lensing: The strong gravitational field of the intervening galaxy bends the light rays towards the Earth (like a lens), and thus we see multiple images of the same quasar in the sky.

TIME DELAY COSMOGRAPHY (CONT.)

Credit: NASA's Goddard Space Flight Center

Time delay: Light rays take **different routes** and travel through **different gravitational potential**, and thus their arrival times can differ → time delay!

TIME DELAY COSMOGRAPHY (CONT.)

Inference on H_0 via an equation for **additional travel distance** (Refsdal, 1964).

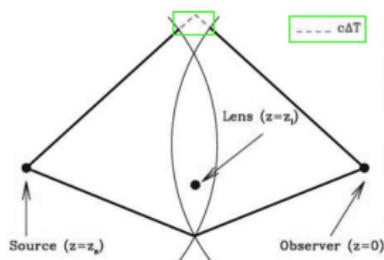
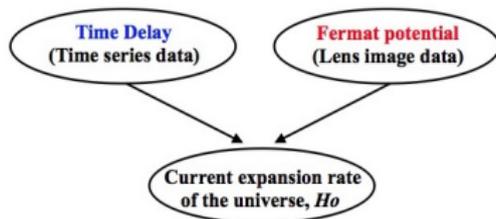


Image Credit: Tommaso Treu (UCLA) in "Dark Matter and Strong Lensing (2014)"

Speed of light (c) \times Time delay (Δt_{ij})
= Time delay distance ($D_{\Delta t}(H_0, z, \Omega)$) \times Fermat potential difference ($\Delta\phi_{ij}$)



CLOSED-FORM MARGINAL POSTERIOR OF H_o

Since $\Delta\hat{\phi}_{ij} = \frac{c\Delta t_{ij}}{D_{\Delta t}(H_o, z, \Omega)}$, Marshall+ (2016) suggest (with fixed z and Ω)

$$\Delta\hat{\phi}_{ij} \mid \Delta t_{ij}, H_o \sim N \left[\frac{c\Delta t_{ij}}{D_{\Delta t}(H_o)}, \sigma_{\Delta\hat{\phi}_{ij}}^2 \right],$$

$$\Delta t_{ij} \sim N(\Delta\hat{t}_{ij}, \sigma_{\Delta\hat{t}_{ij}}^2).$$

$$\text{Marginally, } \Delta\hat{\phi}_{ij} \mid H_o \sim N \left[\frac{c\Delta\hat{t}_{ij}}{D_{\Delta t}(H_o)}, \frac{c^2}{D_{\Delta t}^2(H_o)}\sigma_{\Delta\hat{t}_{ij}}^2 + \sigma_{\Delta\hat{\phi}_{ij}}^2 \right].$$

All but H_o ($\sim \text{Unif}[50, 90]$ a priori) are known or (at least) estimable!

- ▶ $\Delta\hat{\phi}_{ij}$: Fermat potential difference estimate between images i & j .
- ▶ $\sigma_{\Delta\hat{\phi}_{ij}}^2$: An uncertainty estimate (variance) of $\Delta\hat{\phi}_{ij}$.
- ▶ $\Delta\hat{t}_{ij}$: A time delay estimate between images i and image j .
- ▶ $\sigma_{\Delta\hat{t}_{ij}}^2$: An uncertainty estimate (variance) of $\Delta\hat{t}_{ij}$.
- ▶ $D_{\Delta t}(H_o)$: The time delay distance, a deterministic function of H_o .

DATA FOR TIME DELAY

Data for a doubly-lensed quasar are two time series (light curves) with known measurement errors.

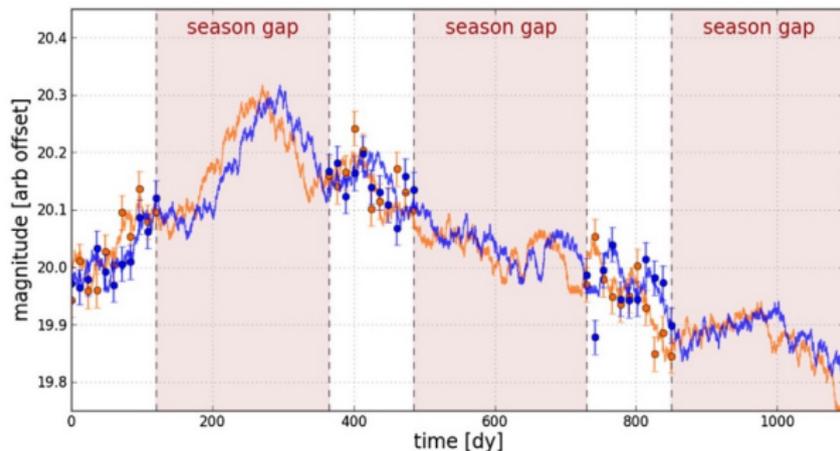


Image Credit: Dobler et al. (2015)

We can estimate Δ by the horizontal shift between two time series.

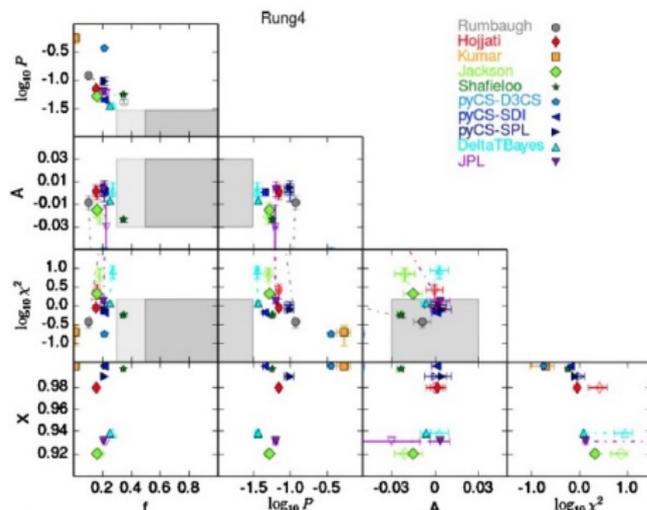
TIME DELAY CHALLENGE

Time Delay Challenge (Dobler et al., 2015; Liao et al., 2015)

- ▶ A blind competition held by 8 astrophysicists from 2013 to 2014.
- ▶ Goal was to **improve existing estimation methods**.
- ▶ 5,000+ simulated data sets with some time delays.
- ▶ 13 teams blindly analyzed the simulated data sets.



Image Credit: HBO website



TIME DELAY LENS MODELING CHALLENGE

Another blind competition to improve lens-modeling methods (Ding+, 2018+).

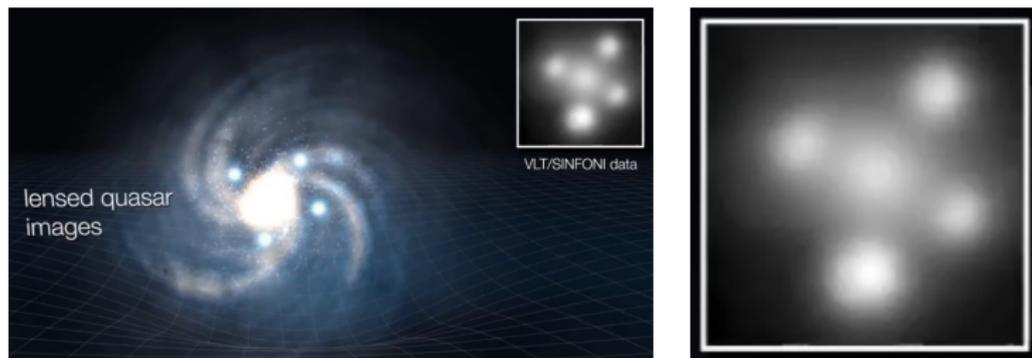


Image Credit: <https://www.youtube.com/watch?v=iE8x9kDHCfo>

Modeling the lens: Lens mass \rightarrow lens potential \rightarrow Fermat potential.
(The mass density is the second derivative of the lens potential.)

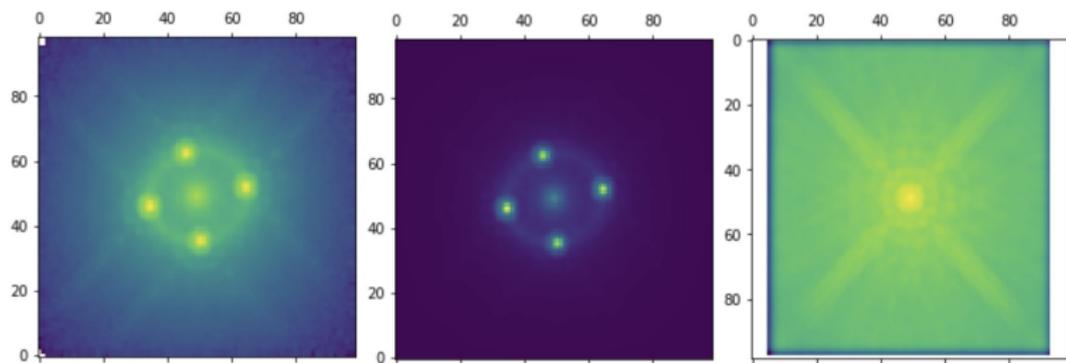
OUTLINE OF TDLMC

The time delay lens modeling challenge is a three-step blind competition composed of four rungs. Each rung shares the same (simulated) Hubble constant. The difficulty increases as we move up higher rungs.

- ▶ **Rung 0**: The true H_0 is disclosed for participant's reference. Two images, one for a doubly-lensed image and the other for a quadruply-lensed image. The point spread function is provided.
- ▶ **Rung 1**: 16 images. **Due was Sep 8**. Real galaxy images for realistic surface brightness are used for simulations.
- ▶ **Rung 2**: 16 images. **Due is Jan 8**. On top of Rung 1's difficulty, a guess of the point spread function is provided for each image.
- ▶ **Rung 3**: 16 images. **Due is May 8**. In addition to all challenges in Rungs 1 and 2, images are generated by massive early-type galaxies.

IMAGE DATA

Image data (from the left): (i) Light intensity (brightness) in 100×100 pixels, (ii) measurement errors, (iii) point spread function (used in (i)).



LENS MODELING

We model (i) lens mass, (ii) lens brightness, and (iii) source brightness.

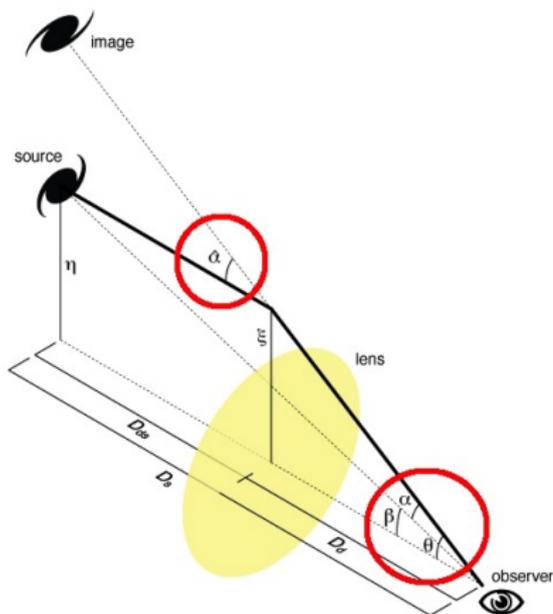


Image Credit: Michael Sachs (from Wiki)

Angular positions (unknown param.)

β : Source position in the absence of the lens.

θ : Lensed image position.

$\hat{\alpha}$: Deflection angle.

$\alpha(\theta)$: Scaled deflection angle for the image at θ .

$\beta = \theta - \alpha(\theta)$: The lens equation.

Given the lens mass distribution, we can infer $\alpha(\theta)$ and β .

LENS MODELING (CONT.)

Outline of lens modeling:

1. Setting (choosing) a lens mass density function, $\Sigma(D_d\theta)$.
2. Deriving a dimensionless surface mass density, $\kappa(\theta) = \Sigma(D_d\theta)/\Sigma_{\text{cr}}$, where Σ_{cr} is the critical surface mass density. For example, with an elliptical power-law mass density,

$$\kappa(\theta_{i1}, \theta_{i2}) = \frac{3 - \gamma'}{2} \left(\frac{\sqrt{q\theta_{i1}^2 + \theta_{i2}^2/q}}{\theta_E} \right)^{1-\gamma'},$$

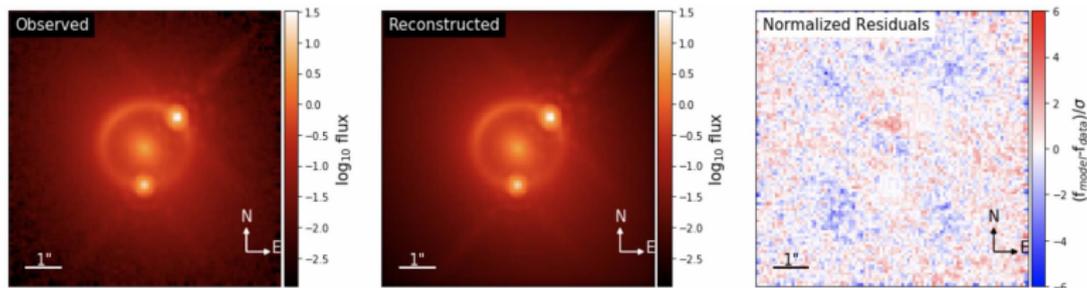
where θ_E is the radius of Einstein ring, q is the ellipticity, and γ' is the radial power-law slope.

3. Computing $\alpha(\theta) = \frac{1}{\pi} \int_{\mathbb{R}^2} d^2\theta' \kappa(\theta') \frac{\theta - \theta'}{|\theta - \theta'|^2}$.
4. Computing lens potential: $\psi(\theta) = \frac{1}{\pi} \int_{\mathbb{R}^2} d^2\theta' \kappa(\theta') \log |\theta - \theta'|$.
5. Finally, the **Fermat potential** is computed as $\phi(\theta) = \alpha(\theta)^2/2 - \psi(\theta)$.

LENS MODELING (CONT.)

The number of unknown parameters is 22 (double) or 28 (quad).

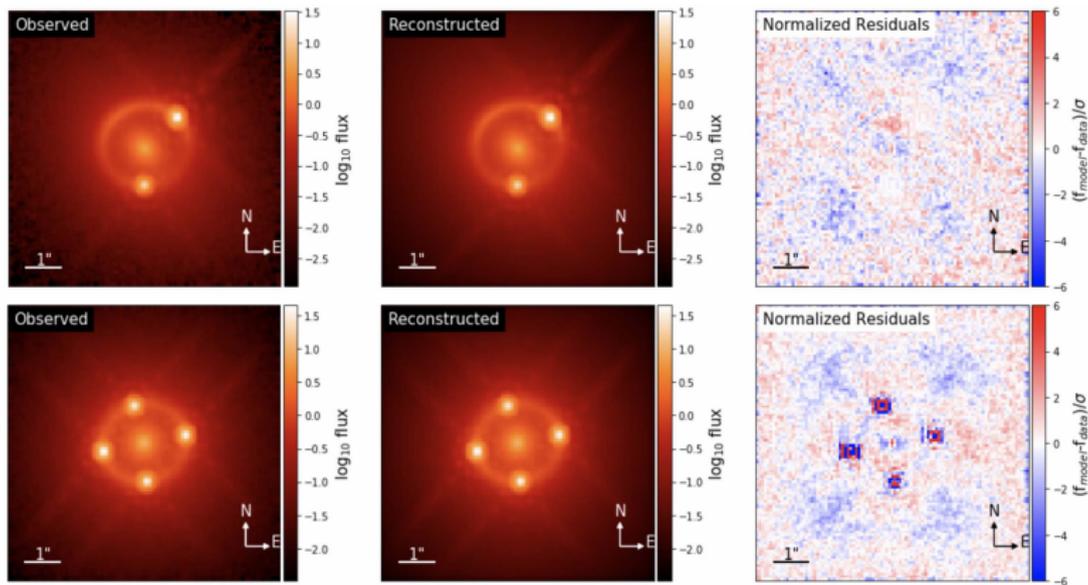
We use a Python package `lenstronomy` (Birrer+, 2015, 2016, 2018) to fit a lens model on the image data. Fitting the model is a two-step procedure; (i) particle swarm optimization to find a global optimum of 20–26 parameters; (ii) MCMC initialized at the global optimum.



Given the observed data (1st), it reconstructs the image (estimate) based on the fitted model (2nd), and shows a residual plot (3rd = 2nd - 1st).

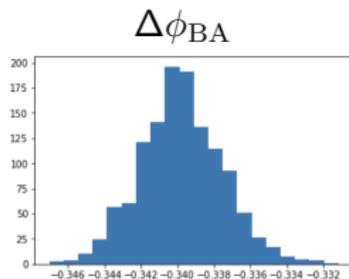
RESULT OF RUNG 0

Observed images (1st column), estimated images (2nd column), and residuals (3rd column).

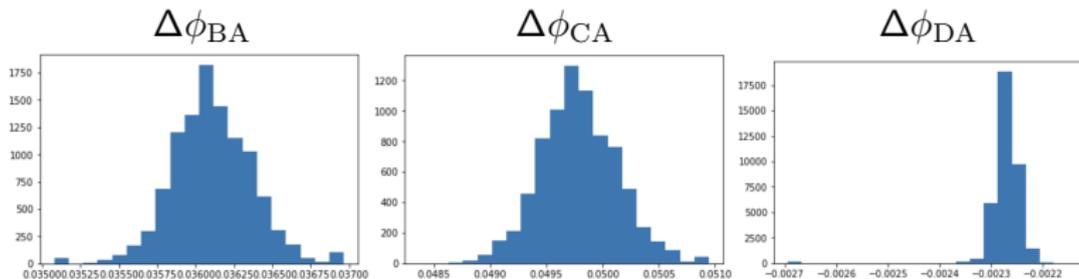


RESULT OF RUNG 0 (CONT.)

Posterior of one Fermat potential difference from a double-image.



Posteriors of three Fermat potential differences from a quad-image.

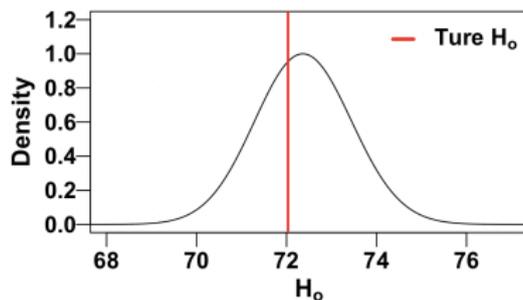


RESULT OF RUNG 0 (CONT.)

The marginal posterior distribution of H_o is closed-form.

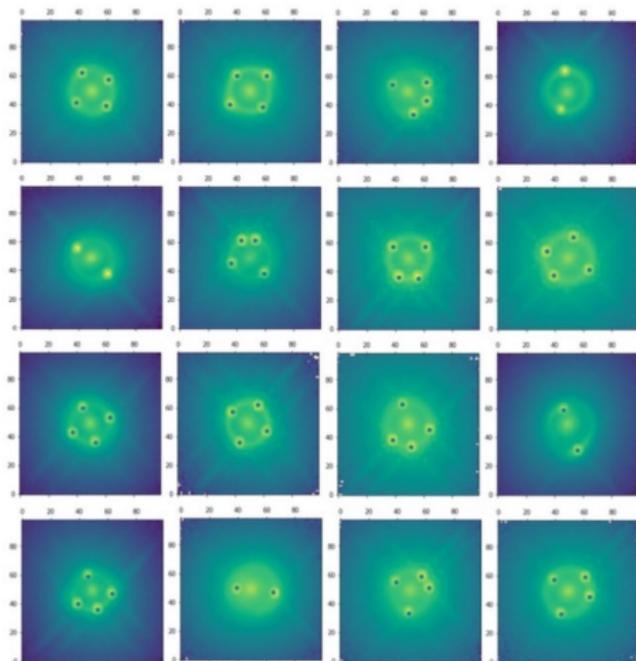
$$\Delta\hat{\phi}_{ij} | H_o \sim N \left[\frac{c\Delta\hat{t}_{ij}}{D_{\Delta t}(H_o)}, \frac{c^2}{D_{\Delta t}^2(H_o)} \sigma_{\Delta\hat{t}_{ij}}^2 + \sigma_{\Delta\hat{\phi}_{ij}}^2 \right].$$
$$H_o \sim \text{Unif}(50, 90).$$

The resulting posterior of H_o based on the **four pairs** of $\Delta\hat{\phi}_{ij}$ and $\sigma_{\Delta\hat{\phi}_{ij}}^2$ (time delays $\Delta\hat{t}_{ij}$ and their uncertainties $\sigma_{\Delta\hat{t}_{ij}}^2$ are given):



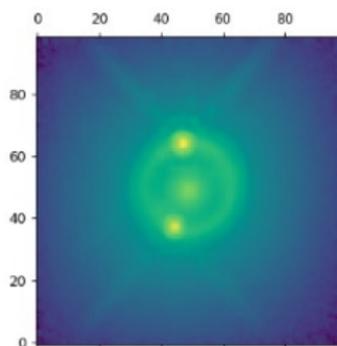
RESULT OF RUNG 1

16 lens image data sets (simulated under the same H_0) to be analyzed.



RESULT OF RUNG 1 (CONT.)

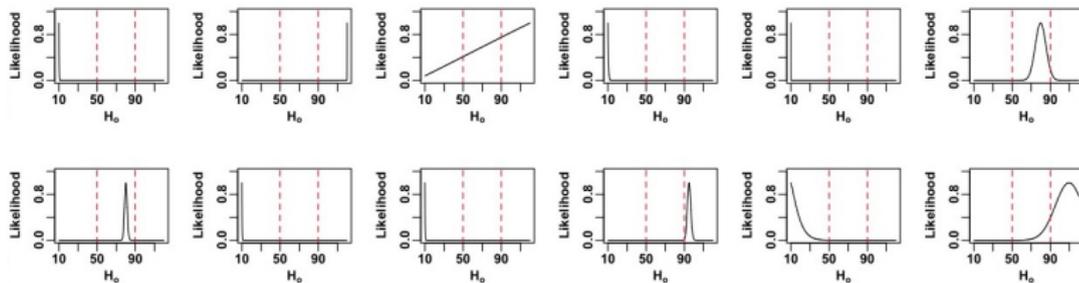
Analytic sequence for **one** image data set as an example.



1. We fit our model on this image data set with **12 variations** each for a combination of **four** different values of point spread function error inflation (1%, 5%, 10%, 20%) and **three** different lens light models (1, 2 or 3 lens light models) → **12 Fermat potential difference estimates and their uncertainties.**

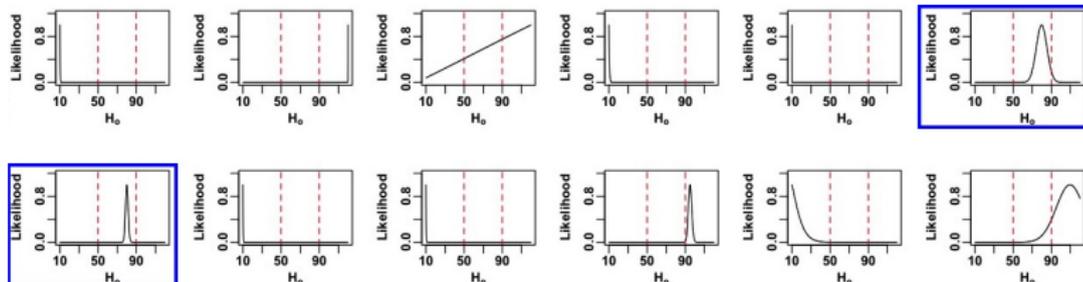
RESULT OF RUNG 1 (CONT.)

2. We derive the posterior of H_o using each pair of Fermat potential difference estimate and uncertainty, leading to 12 posteriors of H_o :



RESULT OF RUNG 1 (CONT.)

3. We collect pairs of Fermat potential estimate and uncertainty that result in the posterior mode of H_o between 50 and 90 (between red vertical dashed lines).



RESULT OF RUNG 1 (CONT.)

4. We take an average of the collected pairs in three ways:

(1) Weighted average and variance

$$\Delta\hat{\phi}_{AB} = \frac{\sum_{i=6}^7 \Delta\hat{\phi}_{AB}^{(i)} / \sigma_{\Delta\hat{\phi}_{AB}^{(i)}}^2}{\sum_{i=6}^7 1 / \sigma_{\Delta\hat{\phi}_{AB}^{(i)}}^2} \quad \text{and} \quad \sigma_{\Delta\hat{\phi}_{AB}}^2 = \frac{1}{\sum_{i=6}^7 1 / \sigma_{\Delta\hat{\phi}_{AB}^{(i)}}^2}.$$

(2) Sample mean of estimates, and sample mean of variance

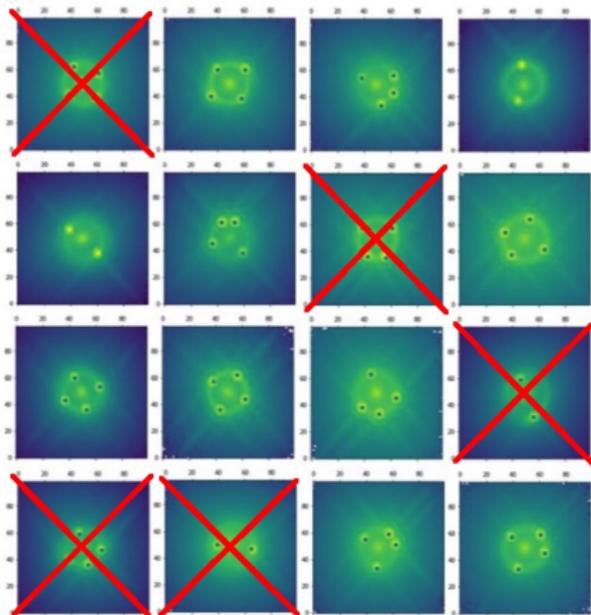
$$\Delta\hat{\phi}_{AB} = \frac{1}{2} \sum_{i=6}^7 \Delta\hat{\phi}_{AB}^{(i)} \quad \text{and} \quad \sigma_{\Delta\hat{\phi}_{AB}}^2 = \frac{1}{2} \sum_{i=6}^7 \sigma_{\Delta\hat{\phi}_{AB}^{(i)}}^2.$$

(3) Sample mean of estimates, and sample variance of estimates

$$\Delta\hat{\phi}_{AB} = \frac{1}{2} \sum_{i=6}^7 \Delta\hat{\phi}_{AB}^{(i)} \quad \text{and} \quad \sigma_{\Delta\hat{\phi}_{AB}}^2 = \sum_{i=6}^7 (\Delta\hat{\phi}_{AB}^{(i)} - \Delta\hat{\phi}_{AB})^2.$$

RESULT OF RUNG 1 (CONT.)

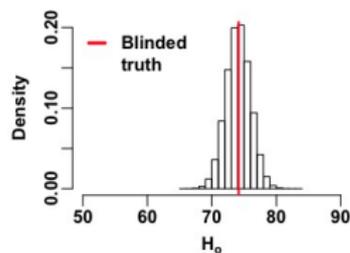
We applied the estimation routine to 16 images and could successfully analyze 11 images out of 16, leading to 25 Fermat potential difference estimates and their uncertainties.



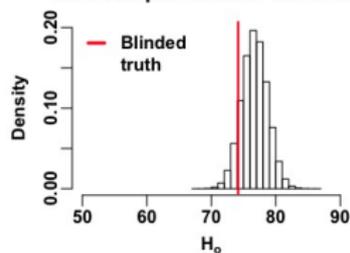
RESULT OF RUNG 1 (CONT.)

The following three estimates are reported:

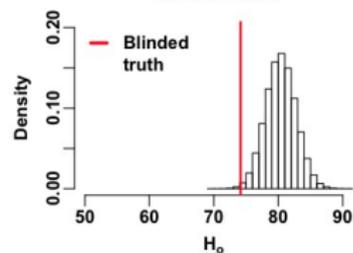
(1) Weighted average



(2) Sample mean of estimates and sample mean of variances

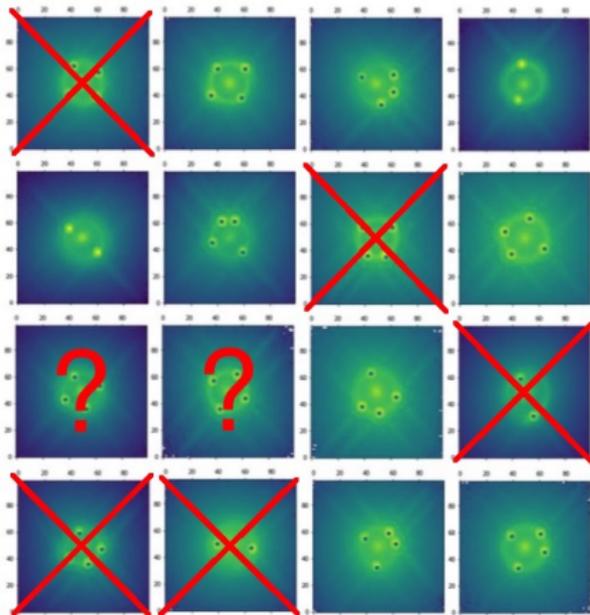


(3) Sample mean and variance of estimates



RESULT OF RUNG 1 (CONT.)

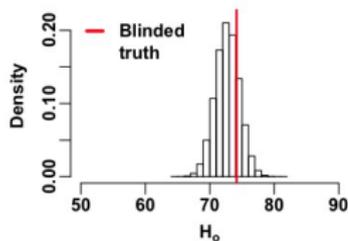
The two lenses below (marked by red question marks) result in the H_o estimates close to 90. What about removing them?



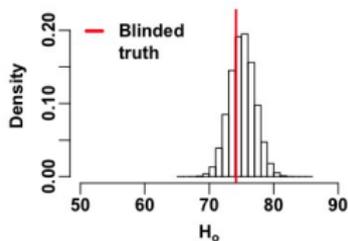
RESULT OF RUNG 1 (CONT.)

The following three estimates are **additionally** reported:

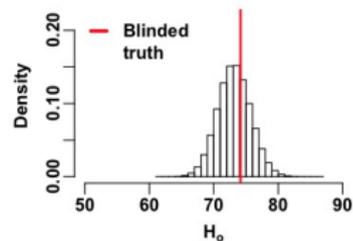
(1) Weighted average



(2) Sample mean of estimates and sample mean of variances



(3) Sample mean and variance of estimates



CONCLUDING REMARKS

Our contribution is to provide a way to combine Fermat potential difference estimates obtained from independent image data sets.

- ▶ The weighted average method works pretty well.
- ▶ The third way to make the representative estimate, i.e., the sample mean and variance of estimates (not using the uncertainty estimates) will not be used for rung 2.
- ▶ For rung 2, I will not put my personal curiosity (no additional three submissions), trusting what the data tell us.
- ▶ The due for rung 2 is Jan 5.