

# Embedding Supernova Cosmology into a Bayesian Hierarchical Model

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ICHASC Talk  
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# Outline

- 1 Algorithm Review
- 2 Combining Strategies
- 3 Surrogate Distribution
- 4 Extensions on Cosmological Model
- 5 Conclusion

# Problem Setting

- **Goal:** Sample from posterior distribution  $p(\psi|Y)$  using Gibbs-type samplers.
- **Special case:** Data Augmentation (DA) Algorithm<sup>1</sup>  
 $\psi = (\theta, Y_{\text{mis}})$ . DA algorithm proceeds as:

$$[Y_{\text{mis}}|\theta'] \longrightarrow [\theta|Y_{\text{mis}}].$$

Stationary distribution:  $p(Y_{\text{mis}}, \theta|Y)$ .

DA algorithm and Gibbs samplers are easy to implement, but. . .  
**Converge slowly!**

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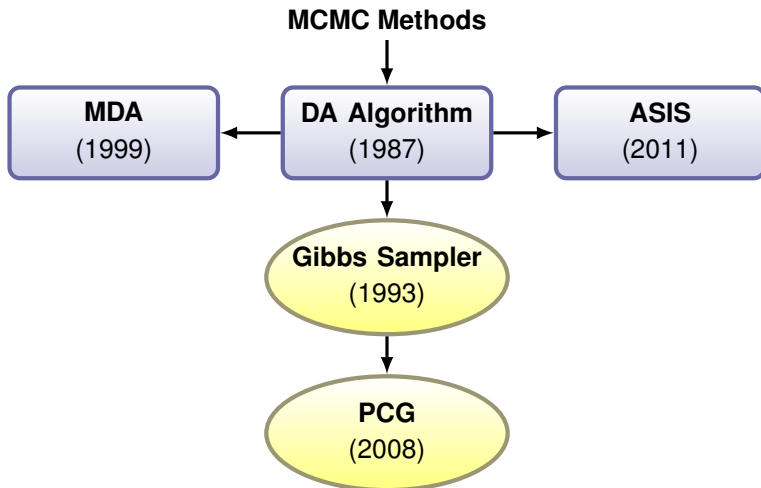
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# Algorithm Review



Blue Rectangle—Expand Parameter Space;  
Yellow Ellipse—Change Conditioning Strategy

# Marginal Data Augmentation

## Marginal Data Augmentation (MDA)<sup>2</sup>

- MDA introduces a working parameter  $\alpha$  into  $p(Y, Y_{\text{mis}}|\theta)$  via  $Y_{\text{mis}}$  [e.g.,  $\tilde{Y}_{\text{mis}} = \mathcal{F}_\alpha(Y_{\text{mis}})$ ], s.t.,

$$\int p(\tilde{Y}_{\text{mis}}, Y|\theta, \alpha) d\tilde{Y}_{\text{mis}} = p(Y|\theta).$$

- If the prior distribution of  $\alpha$  is proper, MDA proceeds as:

$$[\alpha^*, \tilde{Y}_{\text{mis}}|\theta'] \longrightarrow [\alpha, \theta|\tilde{Y}_{\text{mis}}].$$

- MDA improves convergence by increasing variability in augmented data and reducing **augmented information**.

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<sup>2</sup>Meng, X.-L. and van Dyk, D. A. (1999); Liu, J. S. and Wu, Y. N. (1999)

# Ancillarity-Sufficiency Interweaving Strategy

## Ancillarity-Sufficiency Interweaving Strategy (ASIS)<sup>3</sup>

- ASIS considers a pair of special DA schemes:
  - Sufficient augmentation**  $Y_{\text{mis},S}$ :  $p(Y|Y_{\text{mis},S}, \theta)$  is free of  $\theta$ .
  - Ancillary augmentation**  $Y_{\text{mis},A}$ :  $p(Y_{\text{mis},A}|\theta)$  is free of  $\theta$ .
- Given  $\theta$ ,  $Y_{\text{mis},A} = \mathcal{F}_\theta(Y_{\text{mis},S})$ . ASIS proceeds as

Interweave  $[\theta|Y_{\text{mis},S}]$  into DA algorithm w.r.t.  $Y_{\text{mis},A}$

$$\begin{array}{c}
 \Downarrow \\
 [Y_{\text{mis},S}|\theta'] \rightarrow \boxed{[\theta^*|Y_{\text{mis},S}] \rightarrow [Y_{\text{mis},A}|Y_{\text{mis},S}, \theta^*]} \rightarrow [\theta|Y_{\text{mis},A}] \\
 \Updownarrow \\
 [Y_{\text{mis},S}|\theta'] \rightarrow \boxed{[Y_{\text{mis},A}|Y_{\text{mis},S}]} \rightarrow [\theta|Y_{\text{mis},A}]
 \end{array}$$

- ASIS obtains more efficiency by taking advantage of the "beauty-and-beast" feature of two parent DA algorithms.

<sup>3</sup>Yu, Y. and Meng, X.-L. (2011)

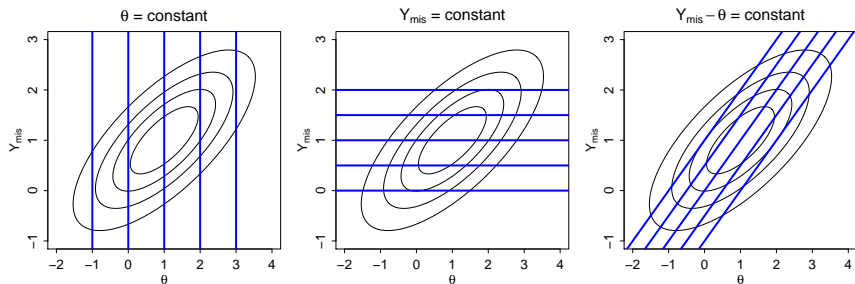
# Understanding ASIS

- Model:

$$Y|(Y_{\text{mis}}, \theta) \sim N(Y_{\text{mis}}, 1), Y_{\text{mis}}|\theta \sim N(\theta, V), p(\theta) \propto 1.$$

- ASIS:  $Y_{\text{mis},S} = Y_{\text{mis}}, Y_{\text{mis},A} = Y_{\text{mis}} - \theta.$

$$[Y_{\text{mis},S}|\theta'] \rightarrow [\theta^*|Y_{\text{mis},S}] \rightarrow [Y_{\text{mis},A}|Y_{\text{mis},S}, \theta^*] \rightarrow [\theta|Y_{\text{mis},A}]$$



More directions: efficient and easy to implement.



# Partially Collapsed Gibbs Sampling

## Partially Collapsed Gibbs (PCG)<sup>4</sup>

- **Model Reduction**: PCG reduces conditioning of Gibbs. It replaces some conditional distributions of a Gibbs sampler with conditionals of marginal distributions of the target.
- PCG improves convergence by increasing variance and jump size of conditional distributions.
- Three stages: *Marginalization*, *permutation*, *trimming*.
  - Tools to transform a Gibbs sampler into a PCG one.
  - Maintain the target stationary distribution.

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<sup>4</sup>van Dyk, D. A. and Park, T. (2008)

# Examples of PCG Sampling

**Example.**  $\psi = (\psi_1, \psi_2, \psi_3, \psi_4)$ ; Sample from  $p(\psi|Y)$ .

## Gibbs

$$p(\psi_1|\psi'_2, \psi'_3, \psi'_4)$$

$$p(\psi_2|\psi_1, \psi'_3, \psi'_4)$$

$$p(\psi_3|\psi_1, \psi_2, \psi'_4)$$

$$p(\psi_4|\psi_1, \psi_2, \psi_3)$$

## PCG I

$$p(\psi_1|\psi'_2, \psi'_3, \psi'_4)$$

$$p(\psi_2, \psi_3|\psi_1, \psi'_4)$$

$$p(\psi_4|\psi_1, \psi_2, \psi_3)$$

## PCG II

$$p(\psi_1|\psi'_2, \psi'_4)$$

$$p(\psi_2, \psi_3|\psi_1, \psi'_4)$$

$$p(\psi_4|\psi_1, \psi_2, \psi_3)$$

- Special cases: **blocked** and **collapsed** Gibbs, e.g., PCG I.
- More interestingly, a PCG sampler consists of *incompatible conditional distributions*, e.g., PCG II. Modifying the order of steps of PCG II may alter its stationary distribution.

# Three Stages to Derive a PCG Sampler

## (a) Gibbs

$$p(\psi_1 | \psi'_2, \psi'_3, \psi'_4)$$

$$p(\psi_2 | \psi_1, \psi'_3, \psi'_4)$$

$$p(\psi_3 | \psi_1, \psi_2, \psi'_4)$$

$$p(\psi_4 | \psi_1, \psi_2, \psi_3)$$

## (b) Marginalize

$$p(\psi_1, \psi_3^* | \psi'_2, \psi'_4)$$

$$p(\psi_2^* | \psi_1, \psi_3^*, \psi'_4)$$

$$p(\psi_2, \psi_3 | \psi_1, \psi'_4)$$

$$p(\psi_4 | \psi_1, \psi_2, \psi_3)$$

## (c) Permute

$$p(\psi_1, \psi_3^* | \psi'_2, \psi'_4)$$

$$p(\psi_2^*, \psi_3 | \psi_1, \psi'_4)$$

$$p(\psi_2 | \psi_1, \psi_3, \psi'_4)$$

$$p(\psi_4 | \psi_1, \psi_2, \psi_3)$$

## (d) Trim [PCG II]

$$p(\psi_1 | \psi'_2, \psi'_4)$$

$$p(\psi_2, \psi_3 | \psi_1, \psi'_4)$$

$$p(\psi_4 | \psi_1, \psi_2, \psi_3)$$

“★”—Intermediate Draws

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# Combining Different Strategies into One Sampler

## Cannot Sample Conditionals?

- Embed Metropolis-Hastings (MH) into Gibbs<sup>5</sup>—standard.
- Embed MH into PCG<sup>6</sup>—subtle implementation!

## Further Improvement in Convergence

- Several parameters converge slowly—a strategy is efficient for one parameter, but has little effect on others; Another strategy has opposite effect. By combining, we improve all.
- One strategy alone is useful for all parameters—prefer to use a combination, as long as gained efficiency exceeds extra computational expense.

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<sup>5</sup>Gilks et al. (1995)

<sup>6</sup>van Dyk, D. A. and Jiao, X. (2015)

# Background

- Physics Nobel Prize (2011): discovery of acceleration of expansion of the universe.
- The acceleration is attributed to existence of **dark energy**.
- **Type Ia supernova** (SN Ia) observations: critical to quantify characteristics of dark energy.

Mass > “**Chandrasekhar threshold**” ( $1.44 M_{\odot}$ )  $\implies$  SN explosion.

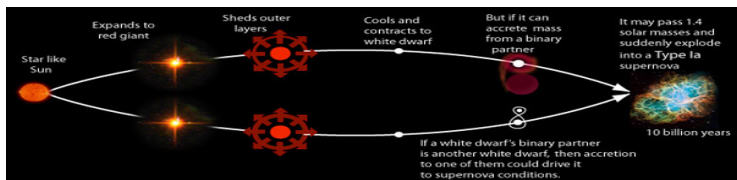


Image credit: <http://hyperphysics.phy-astr.gsu.edu/hbase/astro/snovcn.html>

# “Standardizable Candles”

Common history  $\implies$  similar absolute magnitudes for SNIa, i.e.,

$$M_i \sim N(M_0, \sigma_{\text{int}}^2)$$

$\implies$  SNIa are “standardizable candles”.

Phillips corrections:

$$M_i = M_i^\epsilon - \alpha x_i + \beta c_i, \quad M_i^\epsilon \sim N(M_0, \sigma_\epsilon^2);$$

$x_i$ —stretch correction,  $c_i$ —color correction,

$$\sigma_\epsilon^2 \leq \sigma_{\text{int}}^2$$

# Distance Modulus

Apparent Magnitude – Absolute Magnitude = Distance Modulus:

$$m_B - M = \mu = 5 \log_{10}[\text{distance(Mpc)}] + 25.$$

- Nearby SN: distance =  $zc/H_0$ ;
- Distant SN:  $\mu = \mu(z, \Omega_m, \Omega_\Lambda, H_0)$ ;
  - $c$ —speed of light
  - $H_0$ —Hubble constant
  - $z$ —redshift
  - $\Omega_m$ —total matter density
  - $\Omega_\Lambda$ —dark energy density



# Bayesian Hierarchical Model<sup>7</sup>

- **Level 1:** Errors-in-variables regression:

$$m_{Bi} = \mu_i + M_i^\epsilon - \alpha x_i + \beta c_i;$$

$$\begin{pmatrix} \hat{c}_i \\ \hat{x}_i \\ \hat{m}_{Bi} \end{pmatrix} \sim N \left[ \begin{pmatrix} c_i \\ x_i \\ m_{Bi} \end{pmatrix}, \hat{C}_i \right], \quad i = 1, \dots, n.$$

- **Level 2:**

$$M_i^\epsilon \sim N(M_0, \sigma_\epsilon^2); \quad x_i \sim N(x_0, R_x^2); \quad c_i \sim N(c_0, R_c^2).$$

- **Priors:**

Gaussian for  $M_0, x_0, c_0$ ;

Uniform for  $\Omega_m, \Omega_\Lambda, \alpha, \beta, \log(R_x), \log(R_c), \log(\sigma_\epsilon)$ .

$z$  and  $H_0$  fixed.

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<sup>7</sup>March et al. (2011)

# Notation and Data

## Notation

- $X_{(3n \times 1)} = (c_1, x_1, M_1^\epsilon, \dots, c_n, x_n, M_n^\epsilon)$ ;
- $b_{(3 \times 1)} = (c_0, x_0, M_0)$ ;
- $L_{(3n \times 1)} = (0, 0, \mu_1, \dots, 0, 0, \mu_n)$ ;
- $T_{(3 \times 3)} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \beta & -\alpha & 1 \end{bmatrix}$ , and  $A_{(3n \times 3n)} = \text{Diag}(T, \dots, T)$ .

**Data:** A sample of 288 SNIa compiled by Kessler et al. (2009).

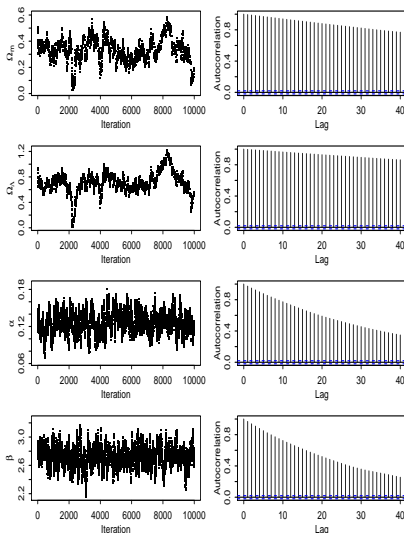
# Algorithms for Cosmological Hierarchical Model

- **MH within Gibbs sampler:** Update of  $(\Omega_m, \Omega_\Lambda)$  needs MH.
- **MH within PCG sampler:**
  - Sample  $(\Omega_m, \Omega_\Lambda)$  and  $(\alpha, \beta)$  without conditioning on  $(X, b)$ .
  - Updates of both  $(\Omega_m, \Omega_\Lambda)$  and  $(\alpha, \beta)$  need MH.
- **ASIS sampler:**  $Y_{\text{mis},S}$  for  $(\Omega_m, \Omega_\Lambda)$  and  $(\alpha, \beta)$ :  $AX + L$ ;  
 $Y_{\text{mis},A}$  for  $(\Omega_m, \Omega_\Lambda)$  and  $(\alpha, \beta)$ :  $X$ .
- **MH within PCG+ASIS sampler:**
  - Given  $(\alpha, \beta)$ , sample  $(\Omega_m, \Omega_\Lambda)$  with MH within PCG;
  - Given  $(\Omega_m, \Omega_\Lambda)$ , sample  $(\alpha, \beta)$  with ASIS.

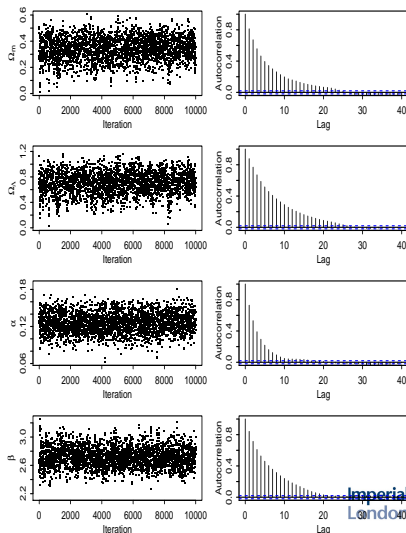
For each sampler, run 11,000 iterations with a burn-in of 1,000.

# Convergence Results of Gibbs and PCG

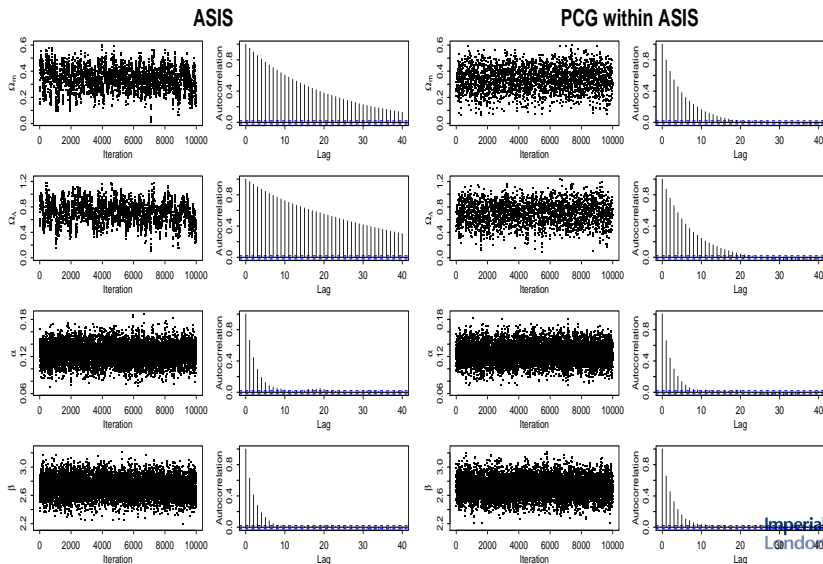
## MH within Gibb



## MH within PCG



# Convergence Results of ASIS and Combining



# Effective Sample Size (ESS) per Second

The larger the ESS/sec, the more efficient the algorithm.

	Gibbs	PCG	ASIS	PCG+ASIS
$\Omega_m$	0.00166	0.0302	0.0103	0.0392
$\Omega_\Lambda$	0.000997	0.0232	0.00571	0.0282
$\alpha$	0.00712	0.0556	0.0787	0.0826
$\beta$	0.00874	0.0264	0.0830	0.0733

# Factor Analysis Model

## • Model

$$Y_i \sim N \left[ Z_i \beta, \Sigma = \text{Diag}(\sigma_1^2, \dots, \sigma_p^2) \right], \text{ for } i = 1, \dots, n.$$

- $Y_i$  —  $(1 \times p)$  vector of the  $i$ th observation;  
 $Z_i$  —  $(1 \times q)$  vector of factors;  $Z_i | \beta \sim N(0, I)$ ;  $q < p$ .
- $\beta$  and  $\Sigma$  — unknown parameters.  
**Priors:**  $p(\beta) \propto 1$ ;  $\sigma_j^2 \sim \text{Inv-Gamma}(0.01, 0.01)$ ,  $j = 1, \dots, p$ .

## • Simulation Study

- Set  $p = 6$ ,  $q = 2$ , and  $n = 100$ .
- $\sigma_j^2 \sim \text{Inv-Gamma}(1, 0.5)$ , ( $j = 1, \dots, 6$ );  
 $\beta_{hj} \sim N(0, 3^2)$ , ( $h = 1, 2; j = 1, \dots, 6$ ).

# Algorithms for Factor Analysis

- **Standard Gibbs sampler:**

$$[Z|\beta', \Sigma'] \longrightarrow \left[ \sigma_j^2 | Z, \beta', \sigma_{-j}^2 \right]_{j=1}^p \longrightarrow [\beta | Z, \Sigma].$$

- **MH within PCG sampler:** sampling  $\sigma_1^2$ ,  $\sigma_3^2$  and  $\sigma_4^2$  without conditioning on  $Z$ . This should be facilitated by MH.

- **ASIS sampler:**  $Y_{\text{mis},A}$  for  $\beta: Z_i$ ;  
 $Y_{\text{mis},S}$  for  $\beta: W_i = Z_i\beta$ .

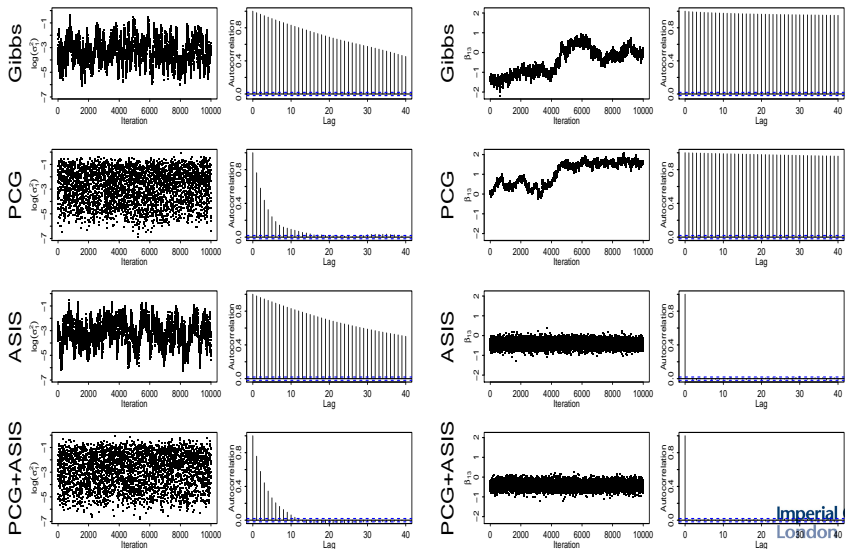
- **MH within PCG+ASIS sampler:**

- Given  $\beta$ , update  $\Sigma$  with MH within PCG;
- Given  $\Sigma$ , update  $\beta$  with ASIS.

For each sampler, run 11,000 iterations with a burn-in of 1,000.



# Convergence Results of Factor Analysis Model



## Effective Sample Size (ESS) per Second

The larger the ESS/sec, the more efficient the algorithm.

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	<b>Gibbs</b>	<b>PCG</b>	<b>ASIS</b>	<b>PCG + ASIS</b>
$\log(\sigma_1^2)$	0.18	2.17	0.15	1.91
$\beta_{13}$	0.0087	0.0090	17.54	15.37

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# Bivariate Surrogate Distribution

**Target distribution:**  $\rho(\psi_1, \psi_2)$ .

**Surrogate distribution:**  $\pi(\psi_1, \psi_2)$ .

$\pi(\psi_1) = \rho(\psi_1)$ ,  $\pi(\psi_2) = \rho(\psi_2)$ ; The correlation between  $\psi_1$  and  $\psi_2$  is lower for  $\pi$  than for  $\rho$ .

## Sampler S.1

$$\rho(\psi_1|\psi'_2)$$

$$\rho(\psi_2|\psi_1)$$

## Sampler S.2

$$\pi(\psi_1|\psi'_2)$$

$$\rho(\psi_2|\psi_1)$$

## Sampler S.3

$$\pi(\psi_1|\psi'_2)$$

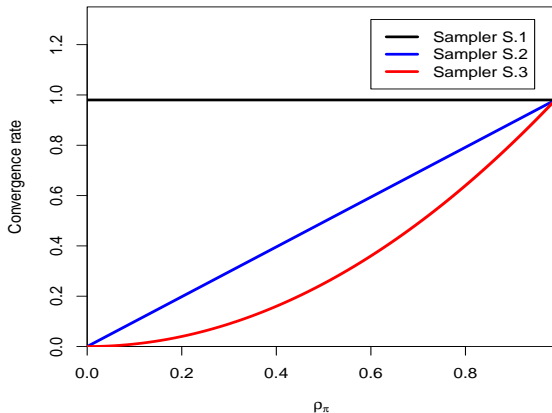
$$\pi(\psi_2|\psi_1)$$

- Stationary distribution of Samplers S.1 and S.2:  $\rho(\psi_1, \psi_2)$ .  
Stationary distribution of Sampler S.3:  $\pi(\psi_1, \psi_2)$ .
- Condition for Sampler S.2 maintaining the target:  
 $\pi(\psi_1) = \rho(\psi_1)$ ,  $\pi(\psi_2) = \rho(\psi_2)$ ; Step order is fixed.

# Comparison of Samplers S.1–S.3

## Example.

$$p(\psi_1, \psi_2) : \mathcal{N} \left[ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & 0.99 \\ 0.99 & 1 \end{pmatrix} \right]; \pi(\psi_1, \psi_2) : \mathcal{N} \left[ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho_\pi \\ \rho_\pi & 1 \end{pmatrix} \right].$$



# Ways to Derive Surrogate Distributions

- **ASIS:**  $[Y_{\text{mis},S}|\theta'] \rightarrow [Y_{\text{mis},A}|Y_{\text{mis},S}] \rightarrow [\theta|Y_{\text{mis},A}]$ .

$$\pi(\theta|Y_{\text{mis},S}) = \int p(Y_{\text{mis},A}|Y_{\text{mis},S})p(\theta|Y_{\text{mis},A})dY_{\text{mis},A};$$

$$\pi(\theta, Y_{\text{mis},S}) = \pi(\theta|Y_{\text{mis},S})p(Y_{\text{mis},S}).$$

- **PCG:** *intermediate stationary distributions.*

$$\text{PCG II: } [\psi_1|\psi'_2, \psi'_4] \rightarrow [\psi_2, \psi_3|\psi_1, \psi'_4] \rightarrow [\psi_4|\psi_1, \psi_2, \psi_3].$$

Intermediate stationary ending with Step 1:

$$\pi(\psi_1, \psi_2, \psi_3, \psi_4) = p(\psi_2, \psi_3, \psi_4)p(\psi_1|\psi_2, \psi_4).$$

- **MDA:**  $[\alpha^*, \tilde{Y}_{\text{mis}}|\theta'] \rightarrow [\alpha, \theta|\tilde{Y}_{\text{mis}}]$ .

$$p(\theta|\tilde{Y}_{\text{mis}}) = \int p(\alpha, \theta|\tilde{Y}_{\text{mis}})d\alpha \xrightarrow{\text{Set } \tilde{Y}_{\text{mis}} \text{ as } Y_{\text{mis}}} \pi(\theta|Y_{\text{mis}});$$

$$\pi(\theta, Y_{\text{mis}}) = \pi(\theta|Y_{\text{mis}})p(Y_{\text{mis}}).$$

# Advantages of Surrogate Distribution

- Surrogate distribution unifies different strategies under a common framework.
- For ASIS, a sampler involving surrogate distribution, but equivalent to the original ASIS sampler, has fewer steps.
- If we are only interested in marginal distributions, surrogate distribution strategy is promising to produce more efficient algorithms.

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# Model Review and New Data

## Recall:

- **Level 1:** Errors-in-variables regression:

$$m_{Bi} = \mu_i + M_i^\epsilon - \alpha x_i + \beta c_i;$$

$$\begin{pmatrix} \hat{c}_i \\ \hat{x}_i \\ \hat{m}_{Bi} \end{pmatrix} \sim N \left[ \begin{pmatrix} c_i \\ x_i \\ m_{Bi} \end{pmatrix}, \hat{C}_i \right], \quad i = 1, \dots, n.$$

- **Level 2:**

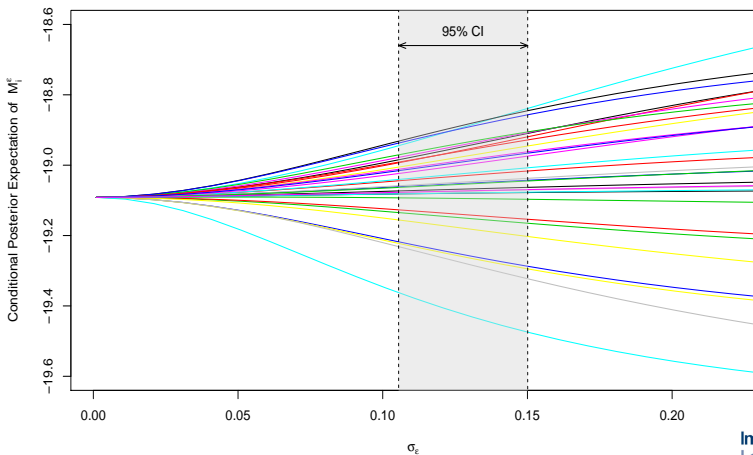
$$M_i^\epsilon \sim N(M_0, \sigma_\epsilon^2); \quad x_i \sim N(x_0, R_x^2); \quad c_i \sim N(c_0, R_c^2).$$

$\sigma_\epsilon$  small  $\implies$  “Standardizable candle”

**Data:** A “JLA” sample of 740 SNIa in Betoule, et al. (2014).

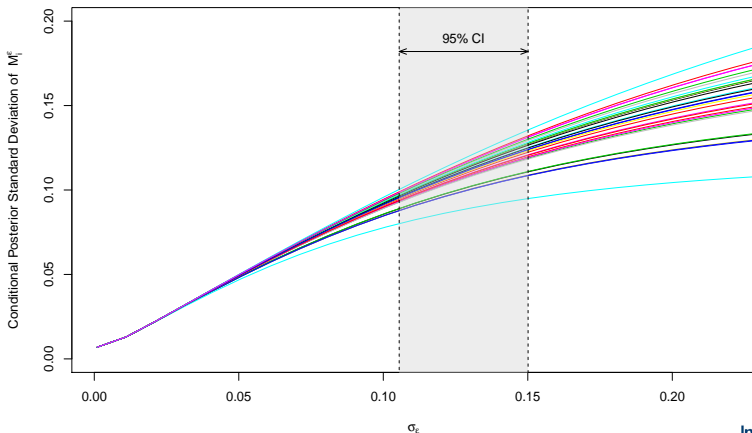
# Shrinkage Estimation

Low mean squared error estimates of  $M_j^\epsilon$



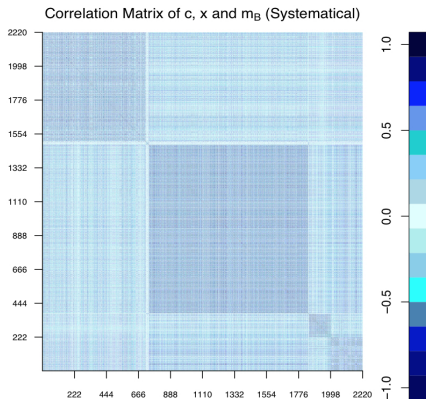
# Shrinkage Error

## Reduced standard deviations



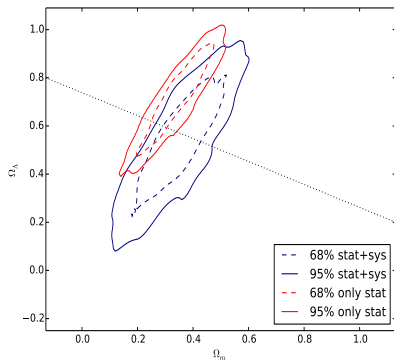
# Systematic Errors

- Systematic errors: seven sources of uncertainties.
- Blocks: different surveys.



Effect on cosmological parameters:

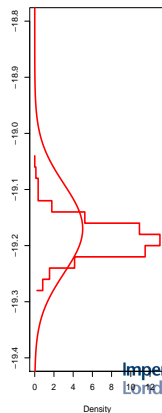
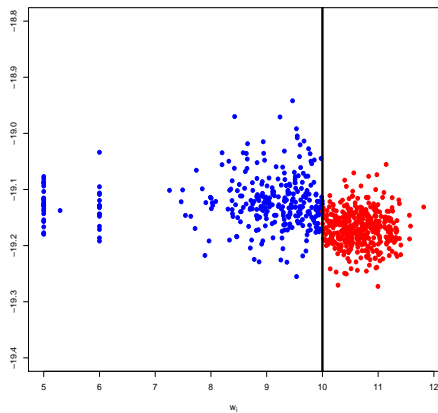
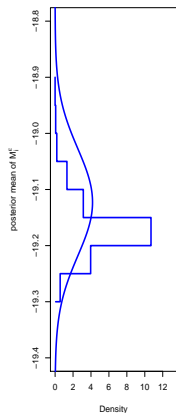
$$\hat{C}_{\text{stat}} \text{ vs } \hat{C}_{\text{stat}} + \hat{C}_{\text{sys}}$$



# Adjusting for Galaxy Mass: Method I

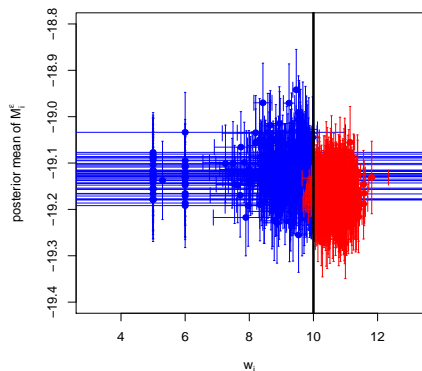
**Method I:** Divide  $M_i^\epsilon$  by  $w_i = \log_{10}(M_{\text{galaxy}}/M_\odot)$ ;

$$\begin{cases} M_i^\epsilon \sim N(M_{01}, \sigma_{\epsilon 1}^2), & \text{if } w_i < 10, \\ M_i^\epsilon \sim N(M_{02}, \sigma_{\epsilon 2}^2), & \text{if } w_i > 10. \end{cases}$$

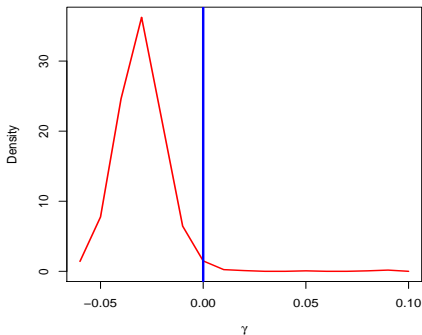


# Adjusting for Galaxy Mass: Method II

Much scatter in both  $M_i$  and  $w_i$ .



Treat  $w_i$  as covariate like  $x_i$  and  $c_i$ ,  
 $\hat{w}_i \sim N(w_i, \hat{\sigma}_w^2)$ :  
 $m_{Bi} = \mu_j + M_j^\epsilon - \alpha x_i + \beta c_i + \gamma w_i$ .



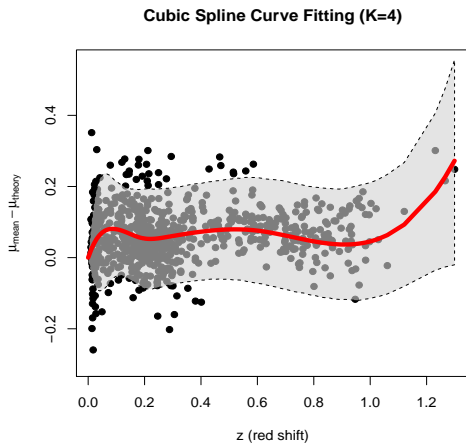
# Model Checking

## Model setting:

- Fix  $(\Omega_m, \Omega_\Lambda)$ ;
- $m_{Bi} = \tilde{\mu}_i + M_i^\epsilon - \alpha x_i + \beta c_i$ ;
- $\tilde{\mu}_i = \mu(z_i, \Omega_m, \Omega_\Lambda, H_0) + t(z_i)$ ,  
 $t(z_i)$ —cubic spline

## Results:

- Red line—posterior mean;
- Gray band—95% region;
- Black dots—  
 $(\hat{m}_{Bi} - M_0 + \alpha \hat{x}_i - \beta \hat{c}_i) - \tilde{\mu}_i$ .



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# Conclusion

## ● Summary

- Combining strategy and surrogate distribution samplers are useful to produce more efficiency in convergence.
- The hierarchical Gaussian model reflects the underlying physical understanding of supernova cosmology.

## ● Future Work

- More numerical examples to illustrate the algorithms.
- Complete the theory of surrogate distribution strategy.
- Embed this hierarchical model into a model for the full time-series of the supernova explosion, using Gaussian process to impute apparent magnitudes over time.