# Exoplanet detection: some statistical challenges 

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## Radial velocity (RV) method



NASA, https://www.nasa.gov/

## Radial velocity (RV) method

NASA, https://exoplanets.nasa.gov/interactable/11/

Stellar activity e.g. spots


NASA, https://www.nasa.gov/

## How do we get the RV times series?

- Observation times: $t_{1}, t_{2}, \ldots, t_{n}$

Single observation - a vector of dimension $p$ :



- Astronomers typically reduce the data to RV time series:



## RV corruption

Corrupted RV =


## Keplerian model for RV due to a planet

Keplerian model e.g. Danby (1988)

$$
\begin{aligned}
M(t) & =\frac{2 \pi t}{\tau}+M_{0} \\
E(t)-e \sin E(t) & =M(t) \\
\tan \frac{\phi(t)}{2} & =\sqrt{\frac{1+e}{1-e}} \tan \frac{E(t)}{2} \\
\text { RV due to planet: } v(t) & =K(e \cos \omega+\cos (\omega+\phi(t)))+\gamma
\end{aligned}
$$

Parameters:

$$
\begin{aligned}
K & =\text { velocity semi-amplitude } \\
\tau & =\text { planet orbital period } \\
M_{0} & =\text { mean anomaly at } t=0 \\
e & =\text { eccentricity } \\
\gamma & =\text { systematic velocity parameter } \\
\omega & =\text { argument of periapsis }
\end{aligned}
$$

## So is it difficult to find a real planet?


http://exoplanets.org

- There are many planets, and large planets and planets with short orbital periods can be easy to find, but Earth-like planets are hard to find
- Some notable detections have turned out to be false positives:
- e.g. Ghost in the time series: no planet for Alpha Cen B, by Rajpaul, Aigrain, \& Roberts (2015)
- In other cases, the strength of evidence for a planet may be (very!) inaccurately quantified - coming next!


## Key tool: SOAP 2.0 simulation software

Dumusque et al 2014: Spot Oscillation And Planet (SOAP) 2.0 radial velocity simulation software.

## White noise model

White noise stellar activity model: $v_{i}=v_{\text {pred }}\left(t_{i} \mid \theta\right)+\epsilon_{i}$, where $\epsilon_{i} \stackrel{i i d}{\sim} N\left(0, \sigma^{2}\right)$
Power for white noise model


## Five challenges

(1) Assessing evidence / Bayes factor estimation
(3) Constructing stellar activity proxies

- RV and stellar activity proxy modeling
- Activity model selection / evaluation
- Analyzing multiple stars jointly

Challenge I: Assessing evidence / Bayes factor estimation

## EPRV III data challenge

## Basic correlated RV noise model

RV observations: $v_{i}=v_{\text {pred }}\left(t_{i} \mid \theta\right)+\epsilon_{i}$
Correlated noise: $\epsilon \sim \operatorname{Normal}(\mathbf{0}, \boldsymbol{\Sigma})$, where

$$
\begin{aligned}
\Sigma_{i, j} & =K_{i, j}+\delta_{i, j}\left(\sigma_{i}^{2}+\sigma_{J}^{2}\right) \\
K_{i, j} & =\alpha^{2} \exp \left[-\frac{1}{2}\left\{\frac{\sin ^{2}\left[\pi\left(t_{i}-t_{j}\right) / \tau\right]}{\lambda_{p}^{2}}+\frac{\left(t_{i}-t_{j}\right)^{2}}{\lambda_{e}^{2}}\right\}\right]
\end{aligned}
$$

Likelihood:

$$
\log \mathcal{L}(\theta)=-\frac{1}{2}\left(\mathbf{v}-\mathbf{v}_{\text {pred }}(\theta)\right)^{T} \Sigma^{-1}\left(\mathbf{v}-\mathbf{v}_{\text {pred }}(\theta)\right)-\frac{1}{2} \log |\operatorname{det} \Sigma|-\frac{n_{\text {obs }}}{2} \log (2 \pi)
$$

## Multi-modal posteriors (plus other challenges)

Lomb-Scargle periodogram: essentially looks at the deviance between a sinusodal model and a constant model, e.g., see VanderPlas (2018)


## Estimated Bayes factors: EPRV III data challenge



Nelson et al. (2018)
https://arxiv.org/abs/1806.04683

## Estimated Bayes factors: EPRV III data challenge



## Energy samplers? Period finding methods?

## Equi-energy samplers:

- Equi-energy sampler: Kou, Zhou, \& Wong (2006)
- Generalized Wang-Landau algorithm: Liang (2005), Liang, Liu, \& Carroll (2012), Bornn et al. (2013)
- Additional bridge sampling step: Wang, Jones, \& Meng (2018+)


## Period finding:

- Lomb-Scargle periodogram, Lomb (1976), Scargle (1982)
- Supersmoother, Friedman (1984)
- Conditional entropy, Graham et al. (2013)
- Multi-band case e.g. VanderPlas \& Ivezic (2015)

Yang Chen \& David Jones have done some preliminary investigations in search of an approach that does not involve an exhaustive search

Challenge II: constructing stellar activity proxies

## Physically motivated proxies

## Motivation:

- If we can determine the level of activity, maybe we can work out if the RV signal is due to a planet or not


## Examples:

- Normalized flux
- BIS
- $\log R_{H K}^{\prime}$



## Physically motivated proxies



Figure credit: Rajpaul et al. 2015

## Automated Discovery of Activity Proxies

## Motivation for an automatic approach:

- Not clear that two or three proxies is enough
- For different stars / types of stars it may be best to use different proxies

Davis et al. (2017) investigate the use of PCA coefficients as activity proxies



Figure credit: Davis et al. (2017)

## Automated Discovery of Activity Proxies

Simple insight: we cannot get a pure planet RV signal, but we can get pure stellar activity ... which can potentially help us find a planet in the corrupted RV signal

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## Our modified PCA:

(1) Extract RV: compute the apparent RV component, $w$, and remove it from $Y$

$$
\tilde{Y}=Y-\frac{Y w w^{T}}{\sum_{i}\left|w_{i}\right|^{2}}
$$

(2) Find remaining structure: apply a dimension reduction technique (e.g. PCA) and use the new coordinates as proxies

## Automated Discovery of Activity Proxies

RV corruption and 2 PCA scores:


- Key: a planet will have no effect on the stellar activity proxies (blue signals)

The data we use looks more like this




## Comparison to Rajpaul et al. (2015)

Planet with 7 day orbit


Planet signal $\mathrm{m} / \mathrm{s}$ (\% of stellar activity amplitude)

## Further dimension reduction approaches

For more complex forms of stellar activity, other techniques may extract more of the relevant information:

- Independence component analysis (ICA)
- Diffusion maps

Challenge III: RV and stellar activity proxy modeling (in the case of a single spot)

## Gaussian processes

- Def: a Gaussian process is a stochastic process $X(t), t \in T$ s.t. for any $t_{1}, \ldots, t_{m} \in T$, the vector $\left(X\left(t_{1}\right), \ldots, X\left(t_{m}\right)\right)$ has a multivariate Normal distribution.
- e.g. apparent RV time series $\sim N(0, \Sigma)$
- Quasi-periodic covariance function

$$
\operatorname{Cov}(X(t), X(s))=\exp (-\underbrace{\frac{\sin ^{2}(\pi(t-s) / \tau)}{2 \lambda_{p}^{2}}}_{\text {periodic }}-\underbrace{\frac{(t-s)^{2}}{2 \lambda_{e}^{2}}}_{\text {local }})
$$

## Model from Rajpaul et al. 2015



Figure credit: Rajpaul et al. 2015
Dependent Gaussian processes:

$$
\begin{aligned}
\Delta \mathrm{RV}(t) & =a_{11} X(t)+a_{12} \dot{X}(t)+\sigma_{1} \epsilon_{1}(t) \\
\log R_{H K}^{\prime}(t) & =a_{21} X(t) \quad+\sigma_{2} \epsilon_{2}(t) \\
\operatorname{BIS}(t) & =a_{31} X(t)+a_{32} \dot{X}(t)+\sigma_{3} \epsilon_{3}(t)
\end{aligned}
$$

## Constructing the covariance matrix

$$
\Sigma=\left(\begin{array}{lll}
\Sigma^{(1,2)} & \Sigma^{(1,2)} & \Sigma^{(1,3)} \\
\Sigma^{(2,1)} & \Sigma^{(2,2)} & \Sigma^{(2,3)} \\
\Sigma^{(3,1)} & \Sigma^{(3,2)} & \Sigma^{(3,3)}
\end{array}\right)
$$

- Example: $\Sigma^{(1,2)}$ gives the covariance between observations of $\Delta R V(t)$ and $\log R_{H K}^{\prime}(t)$
- Calculation: we use the fact that

$$
\begin{aligned}
& \operatorname{Cov}(X(t), \dot{X}(s))=\frac{\partial K(t, s)}{\partial s} \\
& \operatorname{Cov}(\dot{X}(t), \dot{X}(s))=\frac{\partial^{2} K(t, s)}{\partial t \partial s}
\end{aligned}
$$

See Theorem 2.2.2 in Adler (2010)

## Rajpaul et al. model applied to GPCA scores: MLE fit



## Overly constrained, causing strange behaviour

Overly constrained, causing strange behaviour


## General class of GP models we consider

$$
\begin{aligned}
& \text { apparent.RV }\left(t_{i}\right)=a_{11} X\left(t_{i}\right)+a_{12} \dot{X}\left(t_{i}\right)+a_{13} \ddot{X}\left(t_{i}\right)+a_{14} Y_{1}\left(t_{i}\right)+\sigma_{i 1} \epsilon_{1}\left(t_{i}\right) \\
& \operatorname{Proxy} 1\left(t_{i}\right)=a_{21} X\left(t_{i}\right)+a_{22} \dot{X}\left(t_{i}\right)+a_{23} \ddot{X}\left(t_{i}\right)+a_{24} Y_{2}\left(t_{i}\right)+\sigma_{i 2} \epsilon_{2}\left(t_{i}\right) \\
& \operatorname{Proxy} 2\left(t_{i}\right)=a_{31} X\left(t_{i}\right)+a_{32} \dot{X}\left(t_{i}\right)+a_{33} \ddot{X}\left(t_{i}\right)+a_{34} Y_{3}\left(t_{i}\right)+\sigma_{i 3} \epsilon_{3}\left(t_{i}\right)
\end{aligned}
$$

- Green shows model proposed by Rajpaul et al. (2015)
- In our approach some of the $a_{i j}$ 's are set to zero

Note: adaptation of Linear Model of Co-regionalization (LMC) e.g. see Journel and Huijbregts (1978), Osborne et al. (2008), and Alvarez and Lawrence (2011)

## Better modeling approaches?

Thoughts / comments:

- Taylor: indefinitely extending the Taylor series approach doesn't seem like a good idea
- Quasi-periodic: in practice, spots will change at least every couple of stellar rotations, so periodic behaviour will constantly be changing
- Mean function: if the mean function is very structured then it may be best to model this more explicitly, rather than using a zero mean GP
- Kernel learning: e.g. spectral density modeled by Gaussian mixture (Wilson \& Adams, 2013), a Bayesian version (Olivia et al. 2016), transform input (time) before applying standard kernel (Wilson et al., 2016)
- Non-stationarity? as spots come and go, stationarity may not be a good assumption

Impossible challenge? learn dependence structure between time series, but also allow the dependence to develop over time.

Challenge IV: model selection / evaluation

## Stage 1: Preliminary model selection

Number of models $=3375$

Goal: short-list adequate stellar activity models for second stage

Criteria for short-listing models:
(1) AIC
(2) BIC
(3) CV criterion

## Typical AIC / BIC 1st ranked model fit






|  | $X$ coeff | $\dot{X}$ coeff | $\ddot{X}$ coeff | $Y$ coeff |
| ---: | ---: | ---: | ---: | ---: |
| apparent.RV | $Y$ | $Y$ |  |  |
| PC1 | $Y$ |  | $Y$ |  |
| $P C 2$ |  | $Y$ |  |  |

## Stage 2: Hypothesis Testing

How much power does the LRT have?

- $H_{0}$ : no planet
- $H_{A}$ : planet

Power computation: null distribution generated via SOAP 2.0 simulations for Sun-like stars with a single spot


Question: How to generate null distribution in general?

- Unknown and time varying activity
- Different types of star


## Detection Power: orbital period $=7$ days

Planet with 7 day orbit


Planet signal $\mathrm{m} / \mathrm{s}$ (\% of stellar activity amplitude)

Challenge V : analyzing multiple stars jointly

## Questions / comments

## Questions:

- If we have multiple "similar" stars, all with their own activity, can we gain from pooling information across stars?
- E.g. can we learn basis vectors to capture activity for this type of star
- Since in practice, we won't know the exact form of activity, we want a way to learn likely forms of activity, so we can integrate over these rather than integrating with respect to our prior on the type of activity


## Possible hierarchical structure



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Thanks! Questions?

